**Setting up Python controlled Arduino systems**

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This is based on the Cronin group work and libraries.

**Note:** if sent with the Arduino Libraries and commanduino-master folders the below is not necessary. Copy all the files in the Arduino Libraries to the folder containing your Arduino Libraries and check if they are available under the sketch → include library tab in the Arduino IDE. After that, simply run the setup.py file in the commanduino-master folder. Then play with some examples.

**Software requirements**

The software requires the following:

* Python 3.6 or higher
* Arduino IDE
* Arduino Command Handler
* Arduino Command Tools
* Commanduino library

1. Install Python from <https://www.python.org/downloads/>
2. Install Arduino IDE from <https://www.arduino.cc/en/Main/Software>
3. Download the repository <https://github.com/croningp/Arduino-CommandHandler>

Download or clone the repository, rename the folder as CommandHandler and move it to your Arduino libraries folder. You need to restart the Arduino IDE for the library to be loaded and recognized by Arduino. Double check that the CommandHandler library is available under the sketch → include library tab.

Please refer to <https://www.arduino.cc/en/Guide/Libraries#toc5> for manual installation of libraries.

1. Download the repository <https://github.com/croningp/Arduino-CommandTools>

This is a collection of libraries for Arduino to be used with most projects. The libraries can be copied into your Arduino library folder. Double check that they are available under the sketch → include library tab.

1. Download the Commanduino Library from <https://github.com/croningp/commanduino>

This is a Python library for controlling Arduino hardware via a Python interface, rather than hardcoding the behaviour into the Arduino itself. Commanduino acts as a more user friendly front-end for the device. By using the [Arduino-CommandTools](https://github.com/croningp/Arduino-CommandTools) and [Arduino-CommandHandler](https://github.com/croningp/Arduino-CommandHandler) libraries in conjunction with Commanduino, you can essentially control any supported Arduino device through Python.

1. To install Commanduino:
   1. First open a command prompt (Windows) or terminal (Linux)
   2. Note the current working directory (location) is displayed next to the cursor. Change the working directory to the same location that Commanduino is currently saved by typing “cd [folder name]” and pressing tab to autocomplete the folder name, then pressing enter. You have to navigate through the folders in sequence, so it may help to open a file explorer to check the route! To go back a level, type “cd ..”. To change to a different disk, simply type the disk letter followed by a colon, e.g. “d:”
   3. Once you have reached the Commanduino location, type “python setup.py install”. This should automatically carry out the installation if you are in the correct directory and Python has been installed.
2. Work through the included examples!